



Rotary Encoder Resolution Table

TTL Signal:

	<u>Multipliers</u>	<u>Multipliers</u>	<u>Multipliers</u>	<u>Multipliers</u>
Encoder	<i>0.5</i>	<i>1</i>	<i>2</i>	<i>4</i>
1000	0.72°	0.36°	0.18°	0.09°
1250	0.576°	0.288°	0.144°	0.072°
1500	0.48°	0.24°	0.12°	0.06°
2000	0.36°	0.18°	0.09°	0.045°
2500	0.288°	0.144°	0.072°	0.036°
3000	0.24°	0.12°	0.06°	0.03°
3600	0.2°	0.1°	0.05°	0.025°
5000	0.144°	0.072°	0.036°	0.018°
9000	0.08°	0.04°	0.02°	0.01°
18000	0.04°	0.02°	0.01°	0.005°
36000	0.02°	0.01°	0.005°	0.0025°
90000	0.008°	0.004°	0.002°	0.001°
180000	0.004°	0.002°	0.001°	0.0005°

Formula to calculate rotary encoder resolution for TTL signals:

$$R = \frac{360^\circ}{p \times TTLfactor \times \left(\frac{N1}{N2}\right)}$$

Where:

R = Resolution in degrees.

p = Pulses per turn of the encoder.

N1 = Number of teeth on ball screw pulley.

N2 = Number of teeth on motor pulley.

TTLfactor = Multiplying factor for TTL signal. → X0.5, X1, X2, X4



Rotary Encoder Resolution Table

1Vpp Signal:

	<u>Multipliers</u>	<u>Multipliers</u>	<u>Multipliers</u>	<u>Multipliers</u>	<u>Multipliers</u>	<u>Multipliers</u>
Encoder	<i>1</i>	<i>5</i>	<i>10</i>	<i>20</i>	<i>25</i>	<i>50</i>
1000	0.36°	0.072°	0.036°	0.018°	0.0144°	0.0072°
1250	0.288°	0.0576°	0.0288°	0.0144°	0.01152°	0.00576°
1500	0.24°	0.048°	0.024°	0.012°	0.0096°	0.0048°
2000	0.18°	0.036°	0.018°	0.009°	0.0072°	0.0036°
2500	0.144°	0.0288°	0.0144°	0.0072°	0.00576°	0.00288°
3000	0.12°	0.024°	0.012°	0.006°	0.0048°	0.0024°
3600	0.1°	0.02°	0.01°	0.005°	0.004°	0.002°
5000	0.072°	0.0144°	0.0072°	0.0036°	0.00288°	0.00144°
9000	0.04°	0.008°	0.004°	0.002°	0.0016°	0.0008°
18000	0.02°	0.004°	0.002°	0.001°	0.0008°	0.0004°
36000	0.01°	0.002°	0.001°	0.0005°	0.0004°	0.0002°
90000	0.004°	0.0008°	0.0004°	0.0002°	0.00016°	0.00008°
180000	0.002°	0.0004°	0.0002°	0.0001°	0.00008°	0.00004°

Formula to calculate rotary encoder resolution for 1Vpp signals:

$$R = \frac{360^\circ}{p \times sfactor \times \left(\frac{N1}{N2}\right)}$$

Where:

R = Resolution in degrees.

p = Pulses per turn of the encoder.

N1 = Number of teeth on ball screw pulley.

N2 = Number of teeth on motor pulley.

sfactor = Multiplying factor for sinusoidal signal. —→ X1, X5, X10, X20, X25, X50